

ENYU ZHAO

☎ (+1) 323-633-1146 ✉ zhaoenyu344@gmail.com 🌐 enyu-zhao.github.io/

EDUCATION

-
- University of Utah** Aug 2025 - Present
Kahlert School of Computing
- Degree: PhD in Computing, AI, **GPA: TBD**
- University of Southern California** Sept 2022 - May 2024
Thomas Lord Department of Computer Science
- Degree: Master of Science in Computer Science, **GPA: 3.91/4**
 - Major Courses: Robotics, Deep Learning for Robotic Manipulation, Machine Learning, Computer Graphics, etc.
- Dalian University of Technology** Sept 2018 - June 2022
Department of Electronic and Electrical Engineering
- Degree: Bachelor of Engineering in Computer Science and Technology, **GPA: 3.77/4**
 - Major Courses: Deep Learning, Algorithm Analysis, Probability and Statistics, Compiler's Principle, etc.

PUBLICATION

-
- The MOTIF Hand: A Robotic Hand for Multimodal Observations with Thermal, Inertial, and Force Sensors**
Hanyang Zhou, Haozhe Lou*, Wenhao Liu*, Enyu Zhao, Yue Wang, Daniel Seita*
- ISER 2025 [\[Paper \(arxiv\)\]](#) [\[Website\]](#)
- HRIbench: Benchmarking Vision-Language Models for Real-Time Human Perception in Human-Robot Interaction**
Zhonghao Shi, Enyu Zhao, Nathaniel Dennler, Jingzhen Wang, Xinyang Xu, Kaleen Shrestha, Daniel Seita, Maja Matarić
- ISER 2025 [\[Paper \(arxiv\)\]](#) [\[Code\]](#)
- ManipBench: Benchmarking Vision-Language Models for Low-Level Robot Manipulation**
Enyu Zhao, Vedant Raval*, Hejia Zhang, Jiageng Mao, Zeyu Shangguan, Yue Wang, Daniel Seita*
- CoRL 2025 [\[Paper \(arxiv\)\]](#) [\[Website\]](#)
- GPT-Fabric: Smoothing and Folding Fabric by Leveraging Pre-Trained Foundation Models**
Vedant Raval, Enyu Zhao*, Hejia Zhang, Stefanos Nikolaidis, and Daniel Seita*
- ISRR 2024. [\[Paper \(arxiv\)\]](#) [\[Website\]](#)
- Time-aware MADDPG with LSTM for multi-agent obstacle avoidance: a comparative study**
Enyu Zhao, Ning Zhou, Chanjuan Liu, Houfu Su, Yang Liu, Jinmiao Cong
- Complex & Intelligent Systems Volume 10, 4141-4155. [\[Paper\]](#)
- Instant Photorealistic Style Transfer: A Lightweight and Adaptive Approach**
Rong Liu, Enyu Zhao, Zhiyuan Liu, Andrew Feng, Scott John Easley
- arXiv preprint arXiv:2309.10011. [\[Paper \(arxiv\)\]](#) [\[Website\]](#)
- SDI: A tool for speech differentiation in user identification**
Muhammad Abdul Basit, Chanjuan Liu, Enyu Zhao
- Expert Systems with Applications, Volume 243, 122866. [\[Paper\]](#)

ONGOING PROJECTS

-
- GPT-Fabric++** May 2024 - present
USC SLURM Lab

- A follow-up work of GPT-Fabric, focusing on enhancing the generalizability of VLMs in fabric manipulation tasks.

EXPERIENCE

USC Sensing, Learning, and Understanding for Robotic Manipulation (SLURM) Lab

Research Assistant

Dec 2023 - May 2025

Los Angeles, United States

- Conducted research on multi-modality large language models and robotics manipulation.

USC Institute for Creative Technologies

Research Scientist Intern

Aug 2023 - May 2024

Los Angeles, United States

- Conducted research on multi-agent and graph neural network.

Cisco Systems China Research & Development Co Ltd

Research Scientist Intern

Jul 2021 - Nov 2021

Shanghai, China

- Conducted research on small-scale computer vision models and development.

SERVICE

Reviewer for 3D Visual Representations for Robot Manipulation workshop

ICRA 2024

Reviewer for Agile Robotics: From Perception to Dynamic Action workshop

ICRA 2024

COURSE PROJECTS

LLM-based Copilot for Enhanced Vehicle Functionality

Mar 2024 - May 2024

- Develop an LLM-powered copilot with advanced capabilities in task decomposition, language understanding, and API coordination for a set of scenarios frequently performed by drivers. [\[Details\]](#)

Modeling Earthquake Damage

Mar 2023 - May 2023

- Build machine learning model for the "Richter's Predictor: Modeling Earthquake Damage" competition and achieved **top 5%** ranking. [\[Details\]](#)

HONORS

- Ph.D. Fellowship from The University of Utah. 2025
- OpenAI Researcher Access Program (\$5000 API credits). 2024
- Meritorious Winner in Mathematical Contest in Modeling. 2021
- DUT Scientific Innovation Prize 2019
- DUT Academic Achievement Prize 2019

TECHNICAL SKILLS

- Programming Language: Python, C++, C, MATLAB
- Frameworks: Pytorch, Tensorflow, ROS, Rllib, Tianshou